Robotics Artificial intelligence Intelligent control Optimization Cybersecurity Industry 4.0





MS510N4.0



Science Fund
This research was supported by the Science Fund of the Republic of Serbia, of the Republic of Serbia

Grant No. 6523109, AI - MISSION4.0, 2020-2022.

M5510N4.0

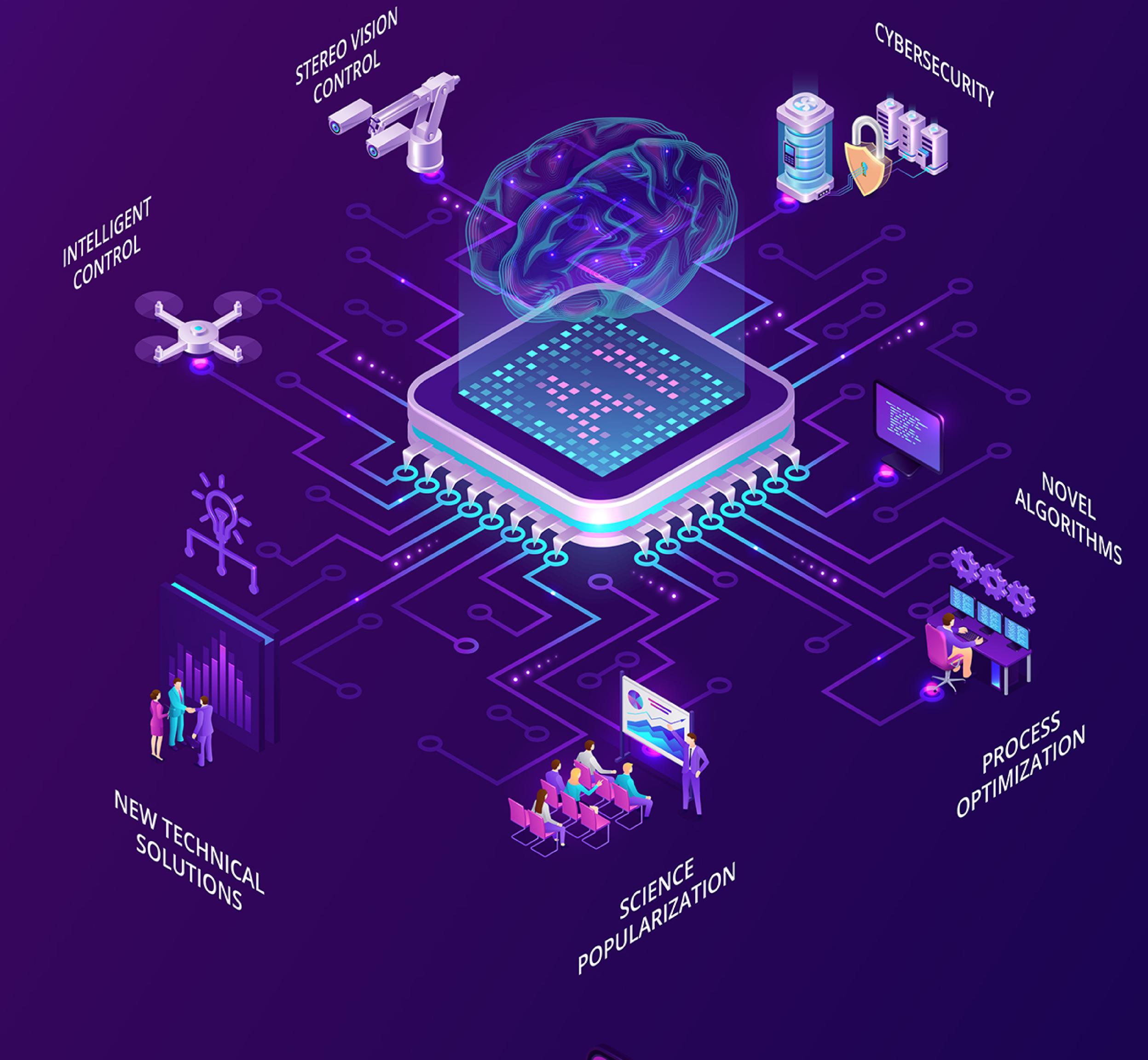
Goals

- 1. Development of the stereo vision-based control algorithms for intelligent mobile robot navigation.
- 2. Dynamic process planning and scheduling of cyber-physical production systems.
- 3. Cybersecurity in continuous-time controlled cyber-physical systems.
- 4. The integration of the developed methodologies to create reconfigurable manufacturing systems.



mission4-0.mas.bg.ac.rs

ARTIFICIAL INTELLICENCE



Scan QR code

For more information about the project scan QR code on your right.







ADDITIONAL ACTIVITES

Flying mobile robot Autonomous mobile robot navigation and mapping for work at heights. Learn more mission4-0.mas.bg.ac.rs



This research was supported by the Science Fund of the Republic of Serbia, Grant No. 6523109, AI - MISSION4.0, 2020-2022.